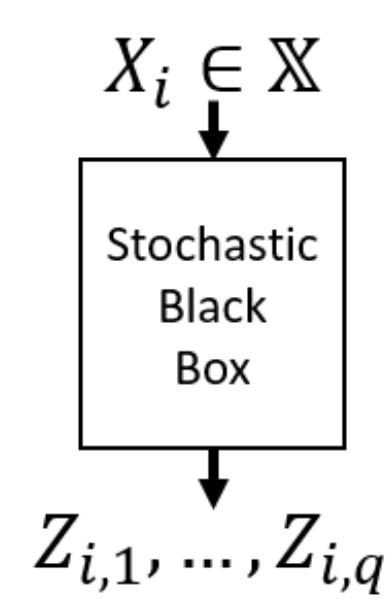




# BAYESIAN MULTI-OBJECTIVE OPTIMIZATION WITH NOISY EVALUATIONS

## 1. CONTEXT

- Multi-objective optimization of the parameters of a planning strategy for the multi-year planning of the electricity distribution grid [DUT15]
- A stochastic black box provides **noisy evaluation results** of the objective functions  $f_1, \dots, f_q$  defined on a discrete search domain  $\mathbb{X} \subset \mathbb{R}^d$
- Previous  $n$  evaluations at  $X = (X_1, \dots, X_n)$  assumed:
  - $Z_{i,1} = f_1(X_i) + \varepsilon_{i,1}, \dots, Z_{i,q} = f_q(X_i) + \varepsilon_{i,q}$   
where  $\varepsilon_{i,j}$ s are zero-mean random variables



## 2. OBJECTIVE

Estimate the **Pareto-optimal solutions** (or Pareto set  $\Gamma$ ) of the problem:

$$x^* = \operatorname{argmin}_{x \in \mathbb{X}} f_1(x), \dots, f_q(x)$$

Defined as:

$$\Gamma = \{x \in \mathbb{X}: \nexists x' \in \mathbb{X} \text{ such that } f(x') \prec f(x)\}$$

where  $\prec$  stands for the Pareto domination rule:

$$y = (y_1, \dots, y_q) \prec y' = (y'_1, \dots, y'_q) \Leftrightarrow \begin{cases} \forall i \leq q, y_i \leq y'_i \\ \exists j \leq q, y_j < y'_j \end{cases}$$

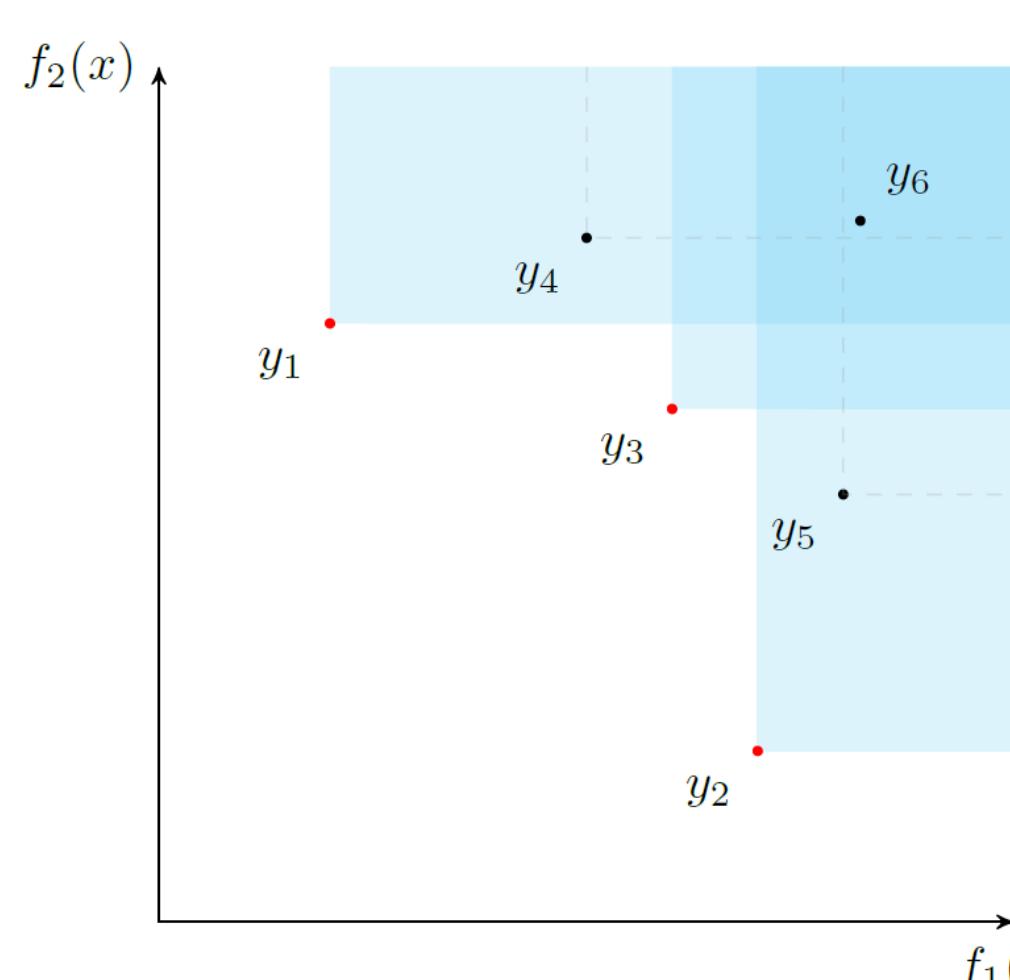


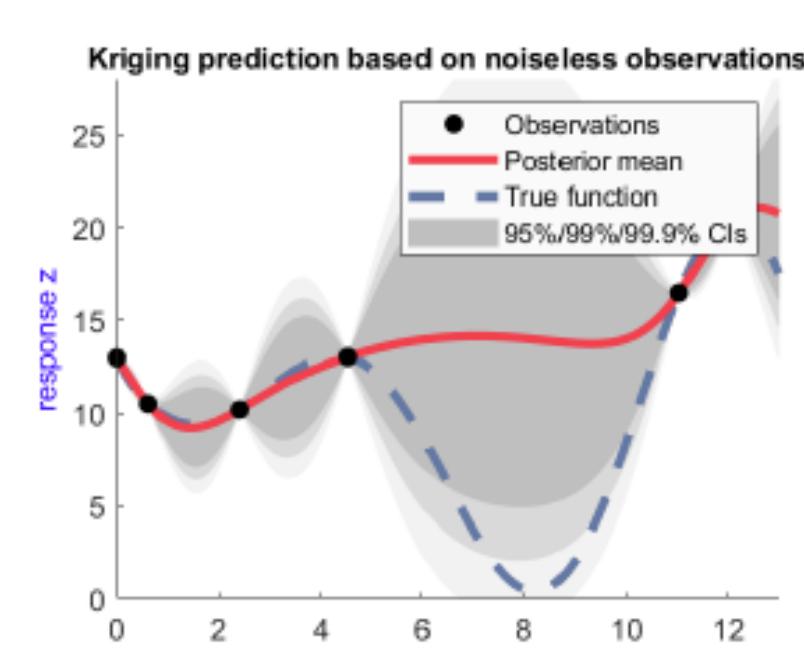
Illustration of the Pareto domination rule

- $y_1, y_2, y_3$  are non-dominated points
- $y_4$  is only dominated by  $y_1$
- $y_5$  is only dominated by  $y_2$
- $y_6$  is dominated by all other points

## 3. BAYESIAN OPTIMIZATION

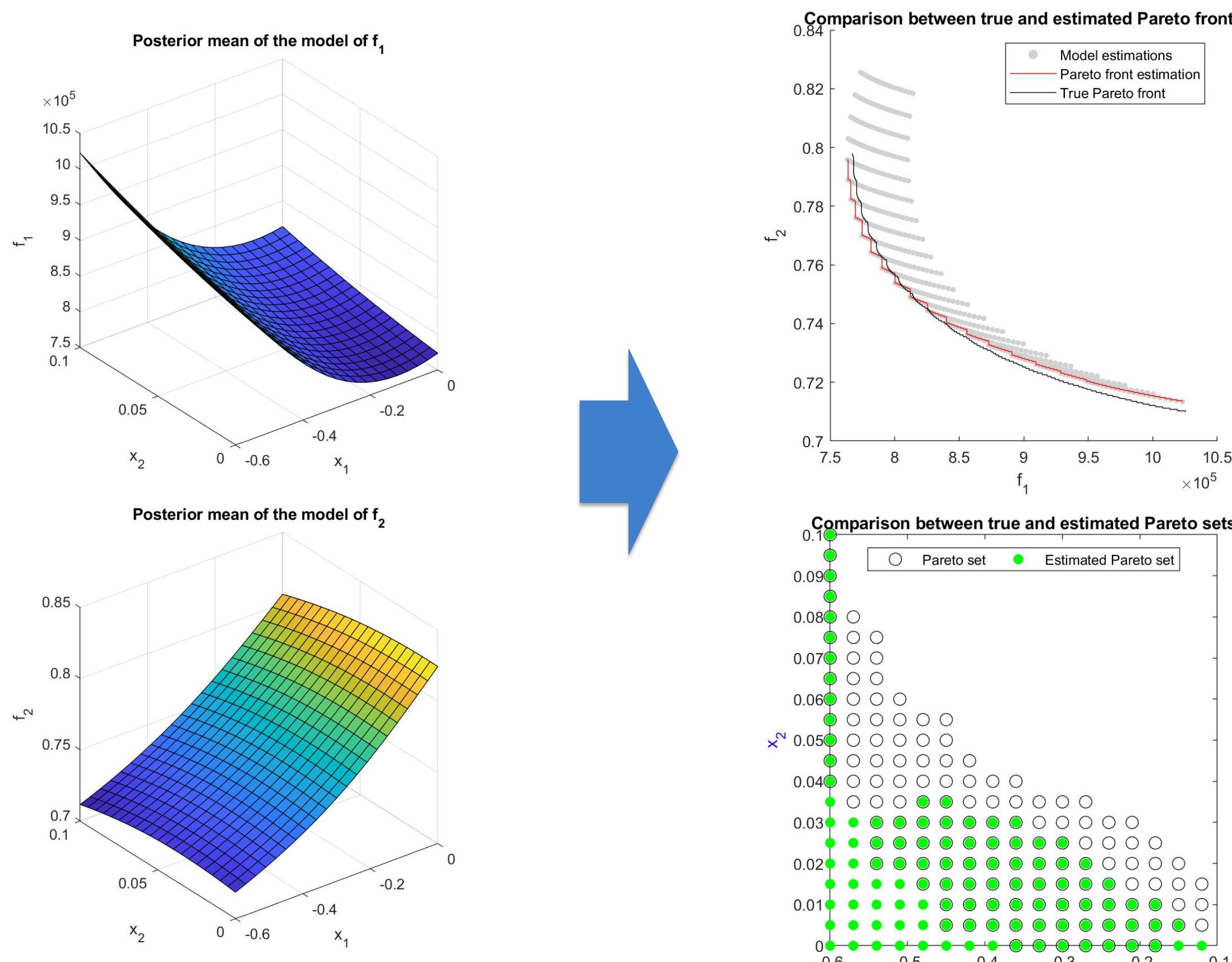
- Define a **probabilistic model** for each  $f$  conditional on previous observations
- Use a **sampling criterion** to select new evaluation points

Provides estimate of  $f$  and a measure of uncertainty of the estimation



### PARETO-OPTIMAL ESTIMATES

Built from the estimates of  $f$



## PROPOSED APPROACH

- Replace the multi-objective problem by the minimization of a single **augmented Tchebycheff function** [KNO06]:

$$\tilde{f}(x) = \max_j [\omega_j f_j(x)] + \rho \sum_j \omega_j f_j(x), \quad \sum_j \omega_j = 1, \rho > 0$$

- At each iteration, generate random weights  $\omega_j$  and apply this function to the  **$n$  previous observations**:

$$\tilde{Z}_i = \max_j [\omega_j Z_{i,j}] + \rho \sum_j \omega_j Z_{i,j}, \quad i = 1, \dots, n$$

- Assume a homoscedastic Gaussian noise model and fit to  $\tilde{Z} = (\tilde{Z}_1, \dots, \tilde{Z}_n)$  a Gaussian Process model  $\xi_n$  with parameters estimated by maximum likelihood

- We use the **Knowledge Gradient (KG)** criterion [FRA09] to select new point  $X_{n+1}$  based on previous observations. The idea is to identify a point that is expected to reduce the minimum of the posterior mean of  $\xi$ :

$$X_{n+1} = \operatorname{argmax}_{x \in \mathbb{X}} KG(x)$$

with:

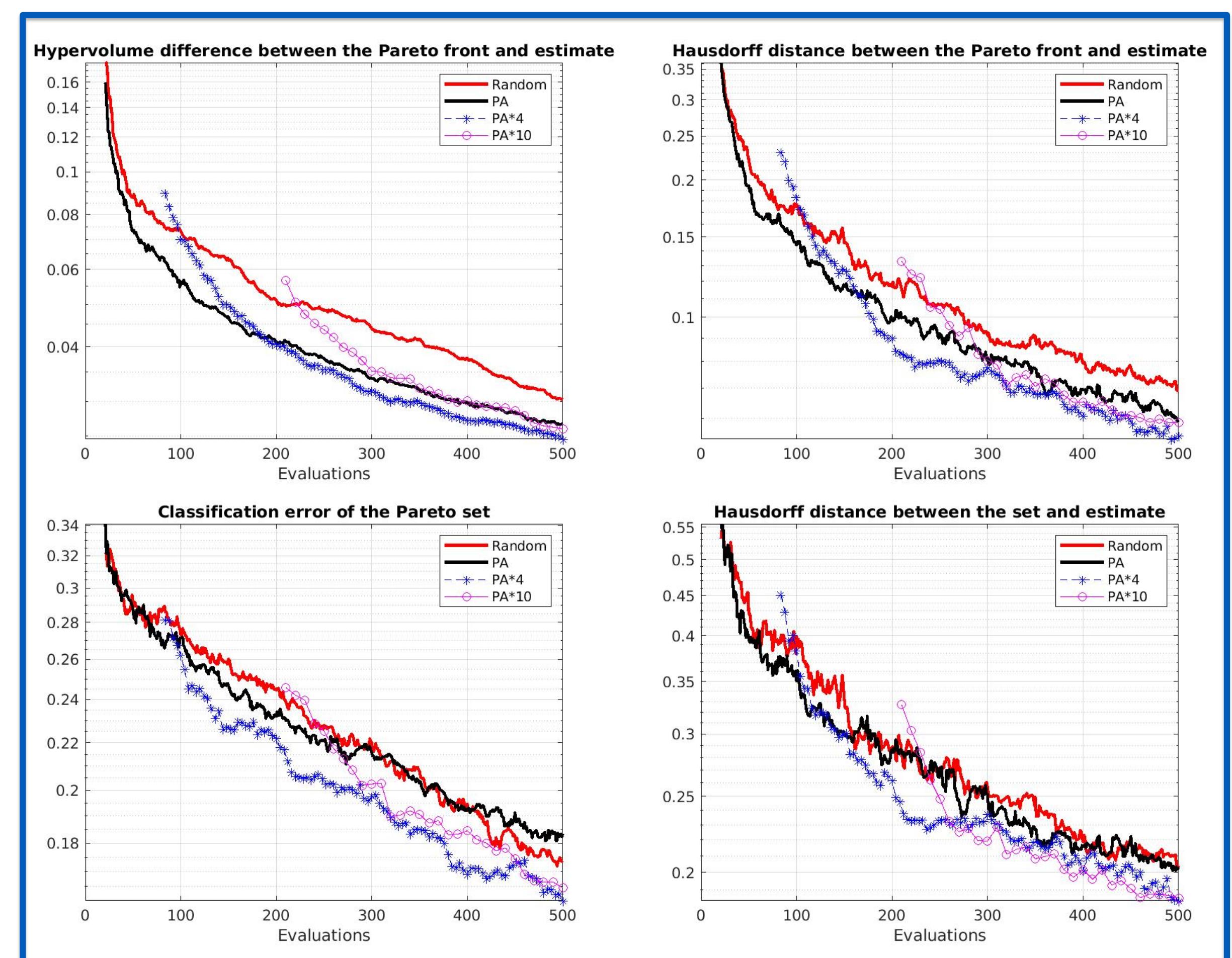
$$KG(x) = \min_{x' \in \mathbb{X}} \mathbb{E}[\xi_n(x')] - \mathbb{E}\left[\min_{x' \in \mathbb{X}} \mathbb{E}[\xi_n(x') | \tilde{Z}_{n,x}]\right]$$

where  $\tilde{Z}_{n,x}$  denotes a new observation of  $\xi_n$  at  $x$

- Update the model with new observation and iterate until stopping criterion is met

## 4. NUMERICAL EXPERIMENTS

- Compare the proposed approach (PA) with random selection of points in a bi-dimensional bi-objective problem
- Compare use of batches of 1, 4 or 10 evaluations



## 5. OPEN QUESTIONS

- ‘Ideal’ batch of evaluations?
- Performance comparison of the proposed approach to other methods in the literature?

## REFERENCES

- [DUT15] Dutrieux, H. (2015). “Méthodes pour la planification pluriannuelle des réseaux de distribution. Application à l’analyse technico-économique des solutions d’intégration des énergies renouvelables intermittentes”. Doctoral Thesis, Ecole Centrale de Lille.
- [FRA09] Frazier, P., Powell, W., and Dayanik, S. (2009). “The knowledge-gradient policy for correlated normal beliefs”. INFORMS Journal on Computing, 21(4):599–613.
- [KNO06] Knowles, J. (2006). “ParEGO: A hybrid algorithm with on-line landscape approximation for expensive multiobjective optimization problems”. IEEE Transactions on Evolutionary Computation, 10(1):50–67.